

Supplementary Material of “Synchronous Membership Function Dependent Event-Triggered H_∞ Control of T-S Fuzzy Systems Under Network Communications”

Bo-Lin Xu ^{ID}, Chen Peng ^{ID}, Senior Member, IEEE, and Wen-Bo Xie ^{ID}, Member, IEEE

APPENDIX

Proof of Theorem 1:

Choose a Lyapunov-Krasovskii functional candidate as

$$\begin{aligned} V(t, x(t)) = & x^T(t) P x(t) + \eta_2^2 \int_{i_k h}^t \dot{x}^T(s) W \dot{x}(s) ds \\ & + \sum_{i=1}^2 \int_{t-\eta_i}^{t-\eta_{i-1}} x^T(s) Q_i x(s) ds \\ & + \sum_{i=1}^2 (\eta_i - \eta_{i-1}) \int_{t-\eta_i}^{t-\eta_{i-1}} \int_s^t \dot{x}^T(v) R_i \dot{x}(v) dv ds \\ & - \frac{\pi^2}{4} \int_{i_k h}^{t-\eta_1} [x(s) - x(i_k h)]^T W [x(s) - x(i_k h)] ds \end{aligned} \quad (16)$$

where $\eta_0 = 0$, the time derivative of $V(t, x(t))$ is

$$\begin{aligned} \dot{V}(t, x(t)) = & 2x^T(t) P \dot{x}(t) + x^T(t) Q_1 x(t) \\ & - x^T(t - \eta_1) Q_1 x(t - \eta_1) + x^T(t - \eta_1) Q_2 x(t - \eta_1) \\ & - x^T(t - \eta_2) Q_2 x(t - \eta_1) + \sum_{i=1}^2 (\eta_i - \eta_{i-1})^2 \dot{x}^T(t) R_i \dot{x}(t) \\ & - \sum_{i=1}^2 (\eta_i - \eta_{i-1}) \int_{t-\eta_i}^{t-\eta_{i-1}} \dot{x}^T(v) R_i \dot{x}(v) dv \\ & + \eta_2^2 \dot{x}^T(t) W \dot{x}(t) + e^T(i_k h) \Phi e(i_k h) - e^T(i_k h) \Phi e(i_k h) \\ & - \frac{\pi^2}{4} [x(t - \eta_1) - x(t - \eta(t))]^T W [x(t - \eta_1) - x(t - \eta(t))]. \end{aligned} \quad (17)$$

For zero-initial state and define J as

$$\begin{aligned} J = & \int_0^{+\infty} y^T(t) y(t) dt - \gamma^2 \int_0^{+\infty} \omega^T(t) \omega(t) dt \\ = & \int_0^{+\infty} (y^T(t) y(t) - \gamma^2 \omega^T(t) \omega(t) + \dot{V}(t, x(t))) dt \\ & - V(+\infty, x(+\infty)) \end{aligned} \quad (18)$$

Lemma 1 and Jensen inequality are adopted to relax the integral term in (17). Define $\varrho^T(t) = [x^T(t), x^T(t - \eta_1), x^T(t - \eta(t)), x^T(t - \eta_2), e^T(i_k h), \omega^T(t)]$, $X = P^{-1}$, $X Q_i X = \widehat{Q}_i$, $X R_i X = \widehat{R}_i$, $X \Phi X = \widehat{\Phi}$, $X U X = \widehat{U}$ and $Y_j = K_j P^{-1}$. Pre- and post-multiply (17) by matrix $\text{diag}\{X \ X \ X \ X \ I \ R_1^{-1} \ R_2^{-1} \ W^{-1} \ I\}$ and its transpose, respectively. Lemma 2 is used to deal with terms $X \widehat{R}_i^{-1} X$ and $X \widehat{W}^{-1} X$. For $V(+\infty, x(+\infty)) \geq 0$, using Schur complement, the sufficient condition for $J < 0$ is

$$\sum_{i=1}^l \sum_{j=1}^l \varrho^T(t) \vartheta_i (\vartheta_j + \epsilon_j) \widehat{\Pi}_{ij} \varrho(t) < 0 \quad (19)$$

where $\widehat{\Pi}_{ij}$ is detailed in Theorem 1. For $S_{ij} > 0$ and condition (12), setting $\vartheta_{ij} = \vartheta_i \vartheta_j$, one can have

$$\begin{aligned} \sum_{i=1}^l \sum_{j=1}^l \vartheta_i (\vartheta_j + \epsilon_j) \widehat{\Pi}_{ij} &= \sum_{i=1}^l \sum_{j=1}^l \vartheta_{ij} [\widehat{\Pi}_{ij} + \epsilon_j (\widehat{\Pi}_{ij} + S_{ij}) - \epsilon_j S_{ij}] \\ &\leq \sum_{i=1}^l \sum_{j=1}^l \vartheta_{ij} \Lambda_{ij} \end{aligned} \quad (20)$$

where Λ_{ij} is detailed in Theorem 1. Utilizing linear piecewise approximation method mentioned in Proposition 1, for $T_{ij} > 0$ and condition (13), a sufficient condition for guaranteeing the negativity of (20) is given as

$$\begin{aligned} \sum_{i=1}^l \sum_{j=1}^l \vartheta_{ij} \Lambda_{ij} &= \sum_{i=1}^l \sum_{j=1}^l (\hat{\vartheta}_{ij} + \Delta \vartheta_{ij}) \Lambda_{ij} \\ &= \sum_{i=1}^l \sum_{j=1}^l [\hat{\vartheta}_{ij} \Lambda_{ij} + \Delta \vartheta_{ij} (\Lambda_{ij} + T_{ij}) - \Delta \vartheta_{ij} T_{ij}] \\ &= \zeta_{\varpi p} \left\{ \sum_{i=1}^l \sum_{j=1}^l [\hat{\vartheta}_{ij}(z_{i_1 \dots i_p \psi}) \Lambda_{ij} + \Delta \vartheta_{ij}(z_{i_1 \dots i_p \psi}) \right. \\ &\quad \left. (\Lambda_{ij} + T_{ij}) - \Delta \vartheta_{ij}(z_{i_1 \dots i_p \psi}) T_{ij}] \right\} \\ &\leq \zeta_{\varpi p} \left\{ \sum_{i=1}^l \sum_{j=1}^l [\hat{\vartheta}_{ij}(z_{i_1 \dots i_p \psi}) \Lambda_{ij} + \Delta \bar{\vartheta}_{ij}(z_{i_1 \dots i_p \psi}) \right. \\ &\quad \left. (\Lambda_{ij} + T_{ij}) - \Delta \bar{\vartheta}_{ij}(z_{i_1 \dots i_p \psi}) T_{ij}] \right\} \end{aligned} \quad (21)$$

where $\zeta_{\varpi p} = \sum_{\varpi=1}^{\varpi} \sum_{i_1=1}^2 \dots \sum_{i_p=1}^2 \prod_{r=1}^p v_{r i_r \psi}(z_r)$. Thus, condition (14) is obtained. Moreover, when using Lemma 1, pre-multiply and post-multiply $\begin{bmatrix} R_2 & * \\ U & R_2 \end{bmatrix} > 0$ by matrix $\text{diag}\{X \ X\}$ and its transpose, respectively. Condition (15) is obtained. ■